

## **PIANC-SMART Rivers 2017**

## e-Navigation for Inland Waterways WG156

Pittsburgh – 20/09/2017 Ir. Dierik Vermeir





#### **Overview**

- Origin and Need for WG156
- Objectives of WG156
- Work programme and Approach WG156

- Final Product WG156
- Findings/Results
- Conclusions and recommendations



## **Origin and Need of WG156**

➢ WG156 is originated from WG125 – Guidelines and recommendations for River Information Services (RIS) - 2011.

WG125 (2011 and before) was really focused on inland waterways. But during the working process it became clear that it could be very useful to look also at the realisations and implementations in the maritime world.

> ToR for WG156 presented to and accepted by PIANC

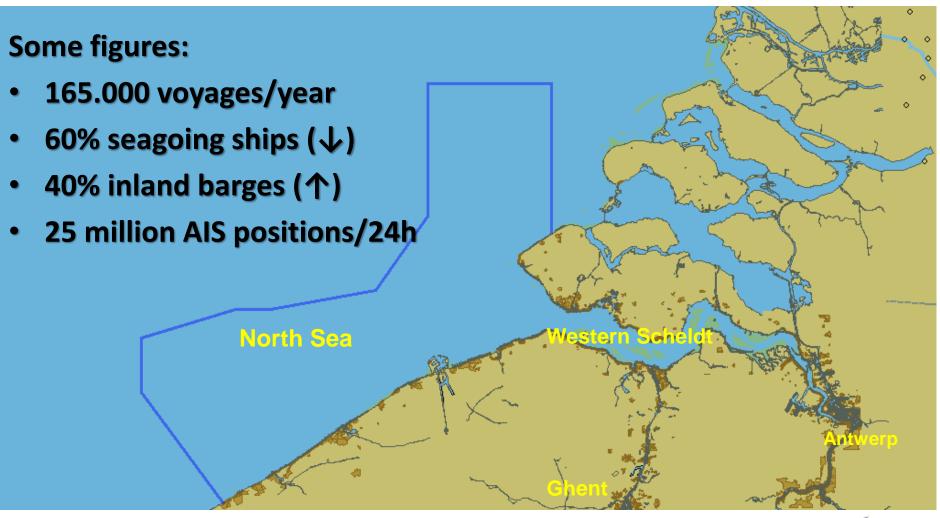


## Why the need?

- The number of <u>mixed mode traffic</u> areas as well as the <u>traffic density</u> itself is constantly increasing. This situation with <u>inland barges and seagoing vessels</u> <u>operating next to each</u> other call <u>for a harmonization of the services and information used for traffic management</u>.
- The <u>growing need for intermodal transport</u> and especially <u>inland navigation</u> could benefit from a <u>more</u> <u>harmonized information exchange</u> between maritime and inland waterborne transport (see also article 1 of the RIS Directive 2005/44/EC).



#### **Example the Western Scheldt River (VL-NL)**





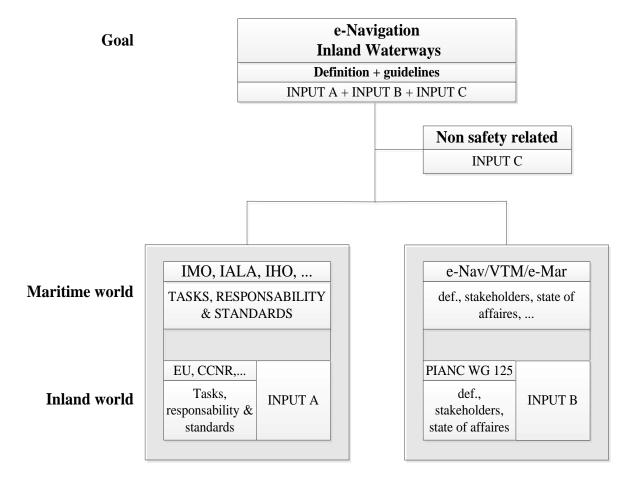


## Main Objectives of WG156

- Provide a definition of e-Navigation for Inland Waterways
- Whether inland navigation could benefit from the developments in the maritime environment.
- In what way the required interaction between maritime transport and inland navigation in this context can be guaranteed to safeguard the required interoperability of future maritime and inland navigation systems.
- ➢ What the implications for River Information Services and the PIANC guidelines on RIS are → WG125



## Work Programme and Approach WG156



**Organisation related** 

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Safety related

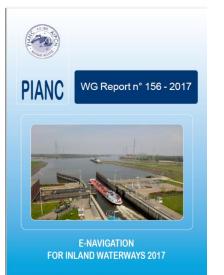


## **Final Product**

#### **Report WG156:**

- Introduction
- Status and Framework for River Information Services
- Status and Framework for e-Maritime and e-Navigation
- Findings/Results of e-Navigation for Inland Waterways

- Conclusions
  - General Conclusions
  - Lessons learned
- ➢ Recommendations (23)







### **Findings/Results**





#### **Definition e-Navigation for Inland Waterways**

- e-Navigation for inland waterways is <u>the framework</u> of information service components based on existing River Information Services (RIS) and RIS Key Technologies
- in order to enable harmonized collection, integration, exchange, presentation and analysis of <u>navigation and</u> <u>logistics</u> related information on board and ashore

#### by <u>electronic</u> means

<u>to enhance</u> safe, efficient, reliable, and environmentally responsible navigation

WG156

on inland waterways and <u>intermodal</u> connections, especially maritime navigation.



Whether RIS could benefit from the developments in e-Navigation in the Maritime World - I:

> Inland Waterways:

RIS Services and RIS Key Technologies

> Maritime world:

> We have the Strategic Implementation Plan (SIP) for e-Navigation for the Maritime World:

- > The 7 pillars concept for e- Navigation
- Maritime Service Portfolios (MSP 16 services) is <u>the framework of</u> information in order to enable harmonized collection, integration, exchange, presentation and analysis of <u>navigation and logistics</u> related information on board and ashore



# Whether RIS could benefit from the developments in e-Navigation in the Maritime World - I:

#### > Inland Waterways:

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## **River Information Services (RIS)**

RIVER INFORMATION SERVICES

Mainly traffic related

- 1 Fairway information Services (FIS)
- 2 Traffic information (TI)
  - a) Tactical traffic information (TTI)
  - b) Strategic traffic information (STI)
- 3 Traffic management (TM)
  - a) Local traffic management (vessel traffic services VTS)
  - b) Lock and bridge management (LBM)
  - c) Traffic Planning (TP)
- 4 Calamity abatement support (CAS)

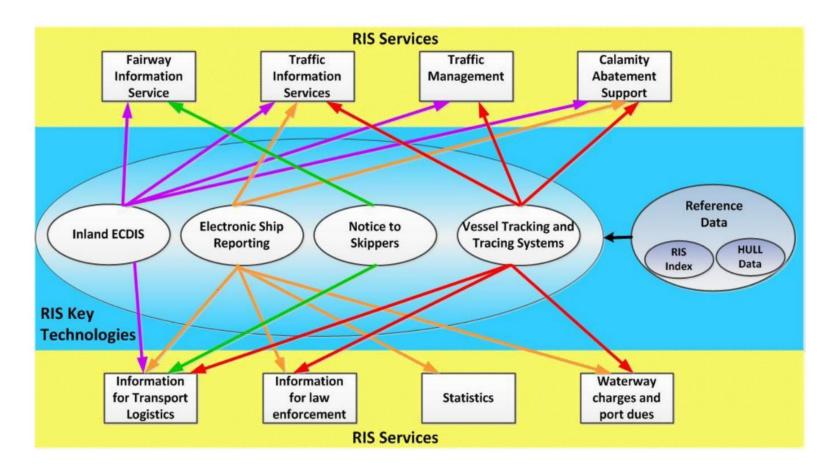
Mainly transport related

- 5 Information for transport logistics (ITL)
  - a) Voyage planning (VP)
  - b) Transport management (TPM)
  - c) Inter-modal port and terminal management (PTM)
  - d) Cargo and fleet management (CFM)
- 6 Information for law enforcement (ILE)
- 7 Statistics (ST)
- 8 Waterway charges and harbour dues (CHD)





### **River Key Technologies & Ref. Data**



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# Whether RIS could benefit from the developments in e-Navigation in the Maritime World - I:

#### > Inland Waterways:

► RIS Services and RIS Key Technologies

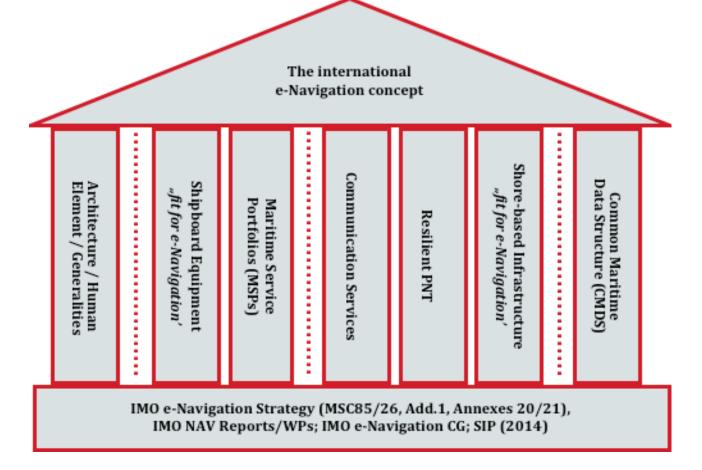
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#### The 7 pillars concept of e-Navigation

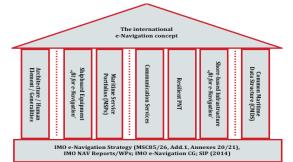




## The 7 pillars concept of e-Navigation

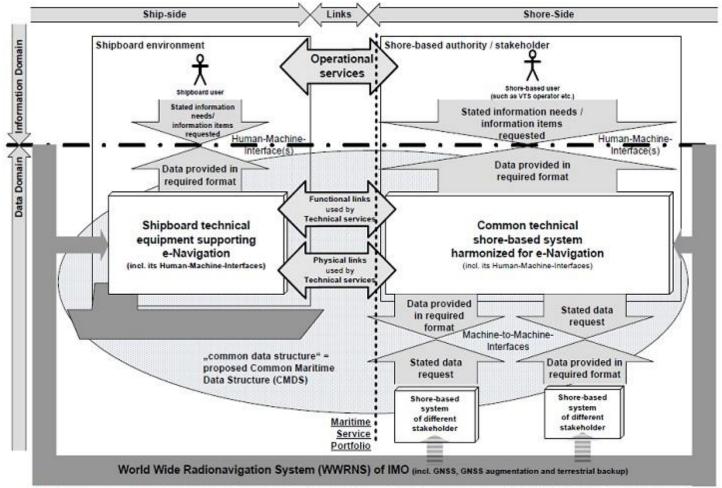
- Architecture/Human Element/Generalities
- Shipboard Equipment "fit for e-Navigation"

- Maritime Service Portfolio's (MSP's)
- Communication Services
- Resilient PNT
- Shore-based Infrastructure
- Common Maritime Data Structure (CMDS)





#### e-Navigation Architecture



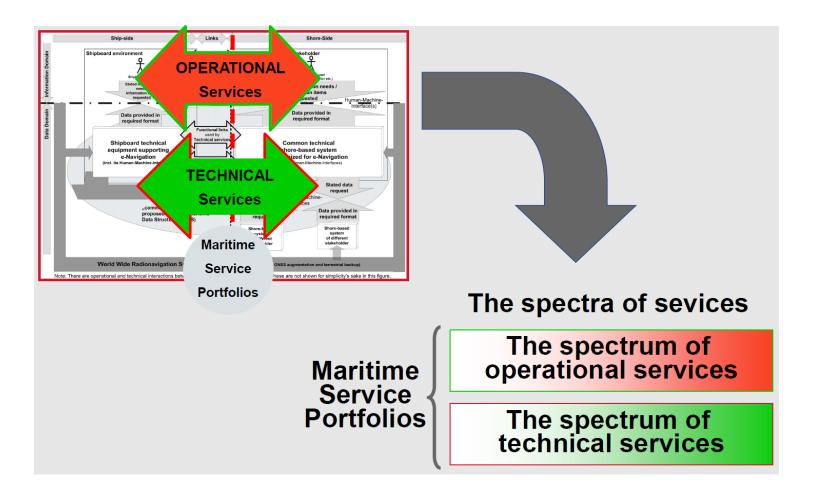
Note: There are operational and technical interactions between different shipboard environments. These are not shown for simplicity's sake in this figure.







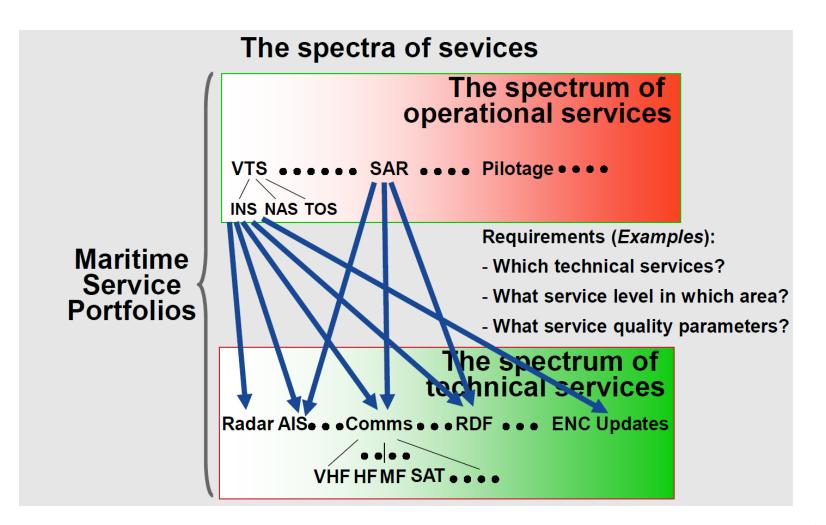
#### **Maritime Service Portfolios - I**



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## **Maritime Service Portfolios - II**





## **Conclusion/Recommendation**

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Inland Waterways (RIS)	Maritime Transport Mode
<b>RIS Services</b>	<b>Operational Services</b>
<b>RIS Key Technologies</b>	Technical Services

#### Recommendation:

In order to facilitate alignment between RIS and maritime e-Navigation, it is recommended to use the same terminology wherever possible or to identify commonalities if different terms are used.





Whether RIS could benefit from the developments in e-Navigation in the Maritime World - I:

## Comparison between:

-RIS Services and the 7 Pillars concept

## -MSP vs. RIS services and vice versa





#### e-Navigation pillars and RIS services relation

-Navigation	pillar
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**Relation with RIS** 

e-Navigation pillar	Relation with RIS
1. Overarching architecture:	
To provide the overarching structural framework	An overarching architecture for RIS does not
for operational functions and technical systems,	exist. For the moment there is the RIS directive,
to allow parallel but coherent and harmonized	the RIS guidelines and four technical directives
development and implementation of the IMO e-	(NtS, AIS, ERI and Inland ECDIS).
Navigation strategy.	
Human Element:	
The human element should not be forgotten as	There is also a need in RIS to take the human
over-reliance on technologies can be dangerous	element into account because there is an
in hazardous situations at sea, and training of	increased introduction of technologies onboard
staff is very important. The administrative burden	and administrative burdens that are similar to the
should be as low as possible for navigating	maritime environment.
personnel.	

parameters for all relevant operational and and operational services. technical services in the maritime domain



Maritime Service Portfolios (MSPs) are one of the seven pillars of e-Navigation and consist of the following services:

- (MSP 1) VTS Information Service (INS);
- (MSP 2) VTS Navigation Assistance Service (NAS);
- (MSP 3) VTS Traffic Organization Service (TOS);

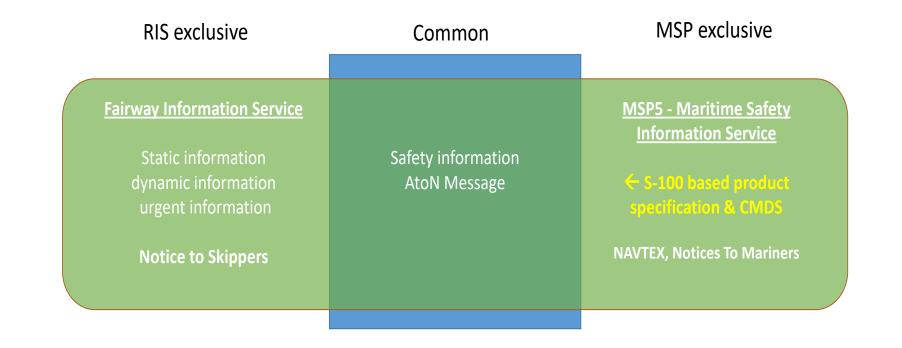
- (MSP 16) Real-time hydrographic and environmental information services
- (MSP 17) Search and Rescue (SAR) Service.

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## **Example Comparison MSP/RIS Services**

#### MSP5 – Maritime Safety Information Service



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Whether RIS could benefit from the developments in e-Navigation in the Maritime World - II:

Relevant e-Navigation Technologies used in the Maritime World usefull for Inland Navigation:

≻ S-100

> CMDS

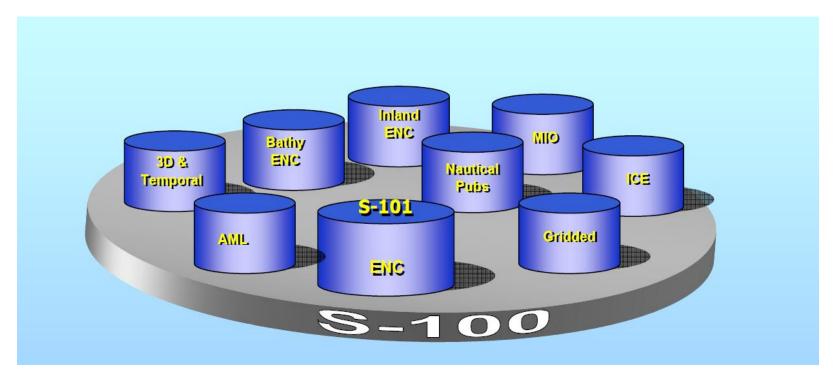
Maritime Cloud

≻SOA



#### **E-navigation developments relevant for inland navigation - I:**

#### S-100 family:

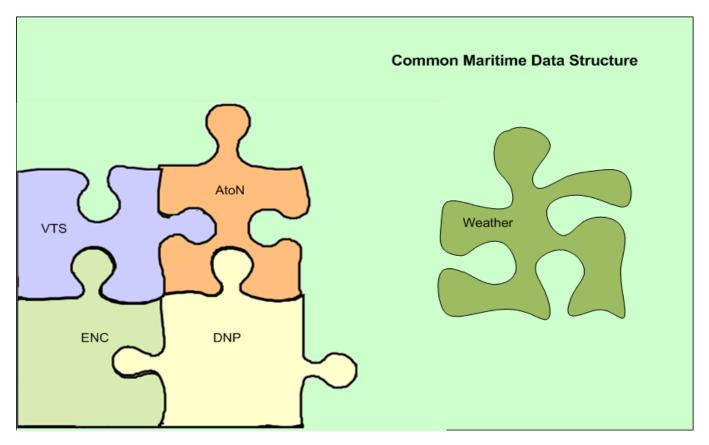


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#### **E-navigation developments relevant for inland navigation - II:**

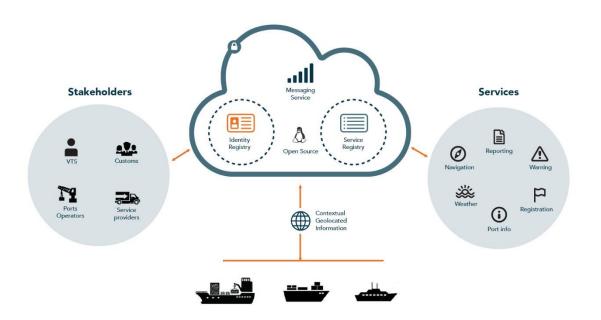
#### The Harmonised Common Maritime Data Structure:





**E-navigation developments relevant for inland navigation - III:** 

#### The Maritime Cloud:



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#### MARITIME CLOUD



## Conclusions

- General Conclusions
- Lessons learned e-Maritime
- Lessons learned e-Navigation in the Maritime WorldMaritime
- e-Navigation for Inland Waterways should be seen as one of the important evolutionary steps in the development of RIS and should not be seen as a separate development/implementation of RIS.





#### **Recommendations - I:**

 Maritime e-Navigation is just at the starting point of implementation, but nevertheless is was possible to formulate <u>23 recommendations</u>.

#### download the report for the details

- <u>Harmonization</u> between the inland and maritime world is very important.
- <u>Further development</u> of e-Navigation for Inland Waterways should be <u>focused on interoperability with maritime e-</u> <u>Navigation</u>.
- Formal coordination between members of RIS and the maritime e-Navigation community <u>should be established</u> (new coordinating body or liaisons between existing bodies).
- <u>Use the same terminology</u> wherever possible or identify commonalities if different terms are used





## **Recommendations - II:**

- Technologies like <u>S-100, CMDS, Maritime Cloud, SOA</u> introduced in the maritime transport mode are very useful for the inland waterways, for example <u>as a building</u> <u>block(s) for a RIS</u> registry(ies).
  - This should also increase the harmonisation and inter-operability between the maritime and inland transport mode.
- Evaluation is made on which <u>recommendations</u> can be useful for <u>WG125</u>.

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 Due to the fact that maritime e-Navigation is still in full development and a lot of RIS related projects are ongoing <u>update report WG156 in 3 to 5 years</u>.



#### Thank you for your attention

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